

Guiding SAM 2 for semantic segmentation of satellite images

Phd colloquium Bonn

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Content

- Introduction
- Methodology
- Experiments
- Conclusion
- Future work and research direction



Motivation

- Topographic databases as a basis for planning and decision making
- Nowadays manual updates based on aerial images every few years
- High temporal resolution of satellite images available
- Neural networks for image analysis
- Foundation Models for a wide range of applications

Why Foundation models?

- Pretrained on large datasets
 - Ability to generalize across different domains
 - Vision Foundation models have strong visual recognition capabilities
- Pretraining enables possibility to save resources and energy for training
- Adaptation to specific tasks is possible
- Here: Segment Anything Model 2

Segment Anything Model 2 (SAM 2) [Ravi2024]

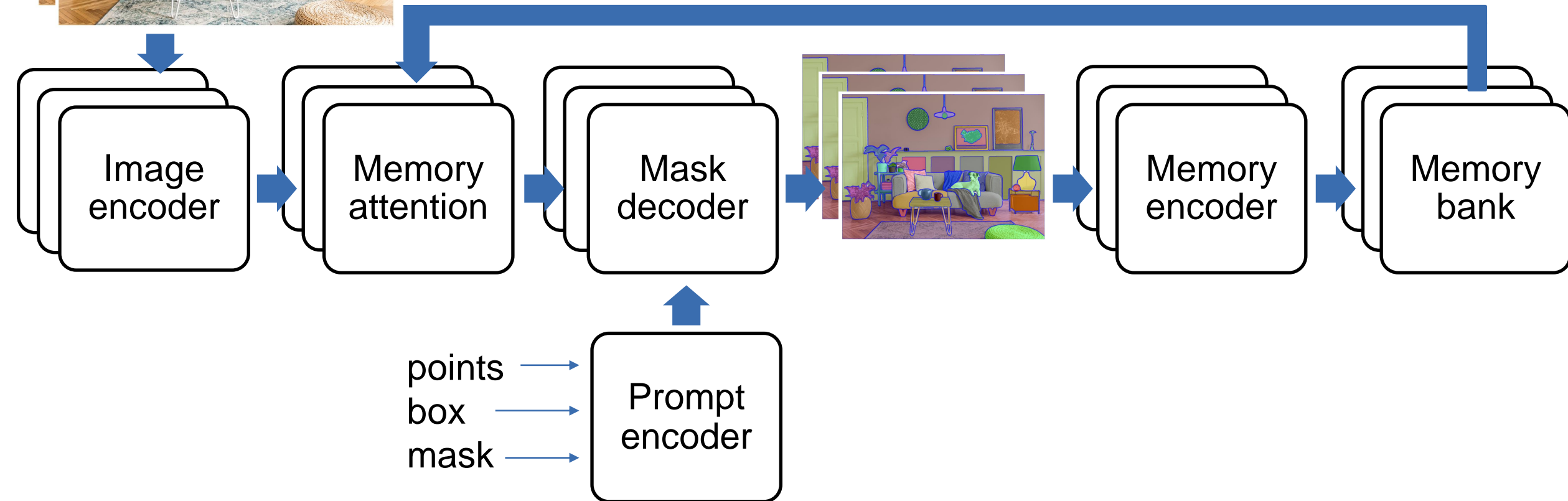
- Promptable visual segmentation in images and videos
- Prompting: Location information about object necessary
- Video segmentation might be useful for satellite image time series



[Segment-anything.com/demo#](https://segment-anything.com/demo#)

SAM 2

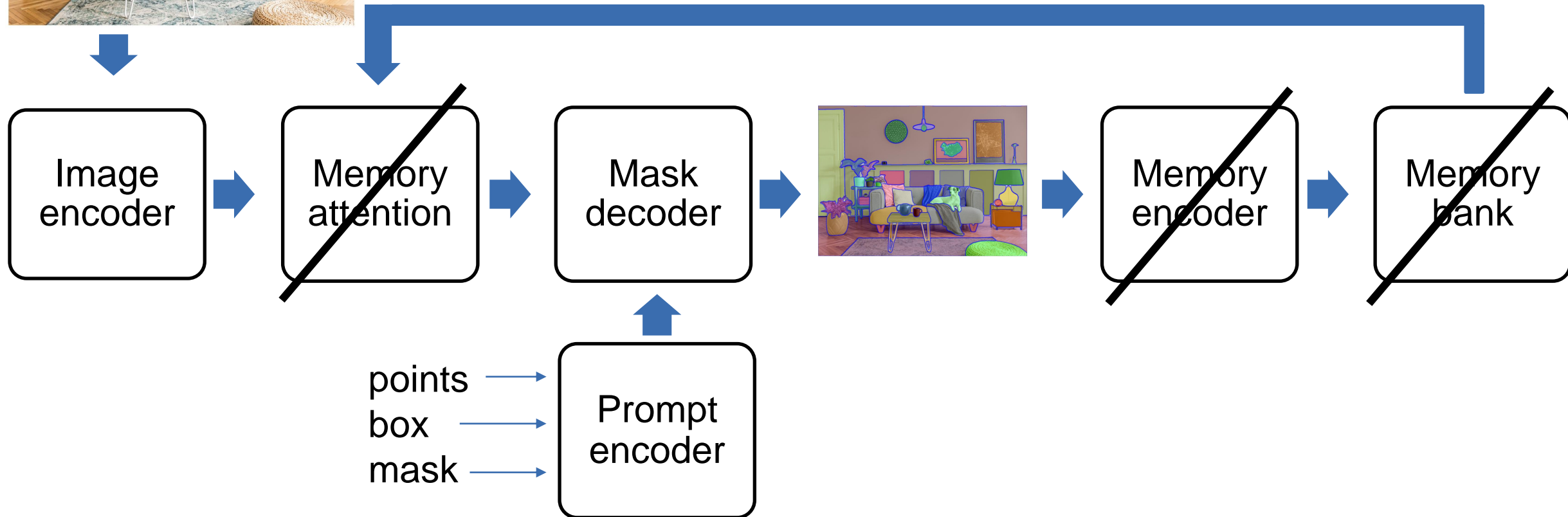
- Hierarchical Vision Transformer
- Automatic mask generator (point grid)



SAM 2



- Hierarchical Vision Transformer
- Automatic mask generator (point grid)



Topographic database - ATKIS

- Authorative Topographic-Cartographic Information System
- Contains polygons and lines with attributes
 - Here: derive prompts and classes



Related Work

- Other works predominantly
 - Use SAM as auxiliary for other networks [Mei2024]
 - Do fine-tuning of parts of the network [Luo2024, Liu2025]
 - Insert adapters for their need [Chen2023, Xie2024, Zhang2025]
 - Work on automatic prompting and prompt refinement [Luo2024, Ren2024, Diab2025]
 - Pre-connect networks to generate prompts
- Focus on images with smaller ground sampling distance than 10 m
 - Use prior knowledge directly as prompts and generate complete semantic segmentation without any adaptation or training

Research Question

- How can we use (pretrained) Foundation Models for semantic segmentation and/or change detection for topographic database updates?
 - Is this working in a zero-shot / few-shot manner with no or very less training data?
 - How can we process image time series?
 - How can conditions about land cover classes be taken into account?
 - How do we transfer semantic segmentation to polygons?
 - This presentation: How good can **semantic segmentation** of **Sentinel-2** images be performed using “Segment Anything Model 2” in a **zero-shot** manner together with **ATKIS** information?

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Method - Overview

ATKIS objects



Sentinel-2 image



SAM 2

per class
segmentation

prompt
generation

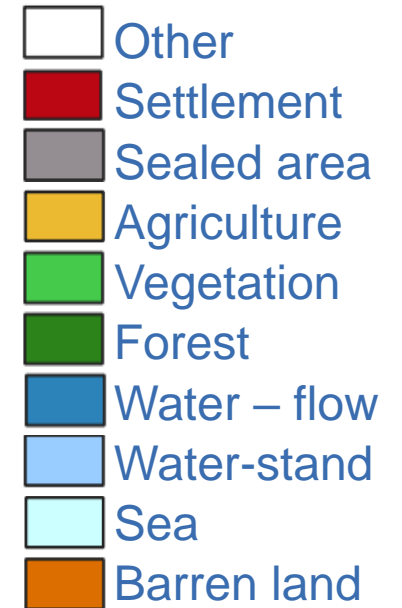
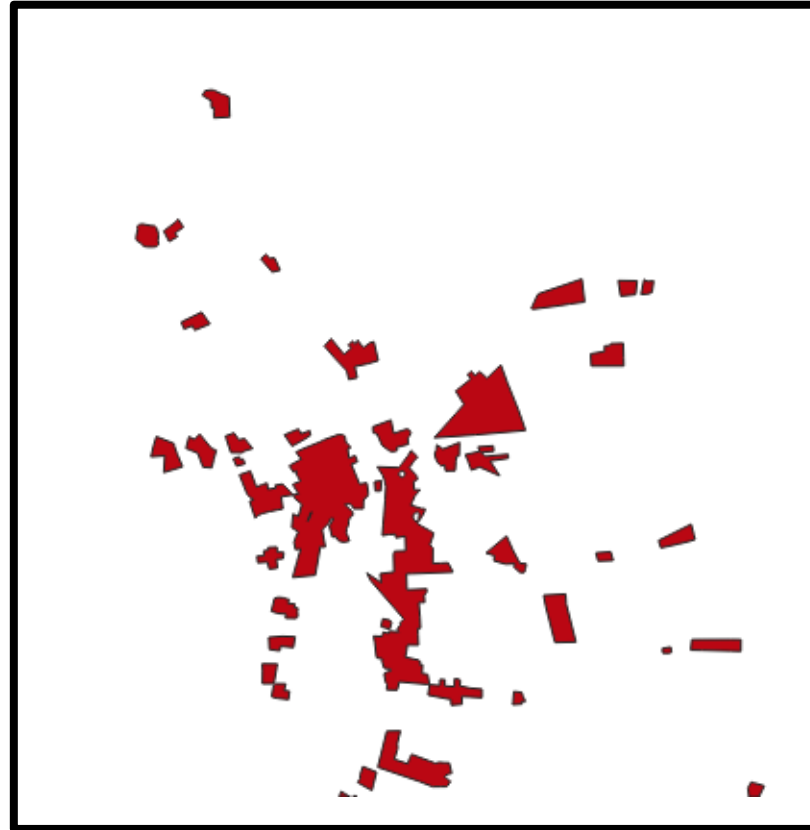
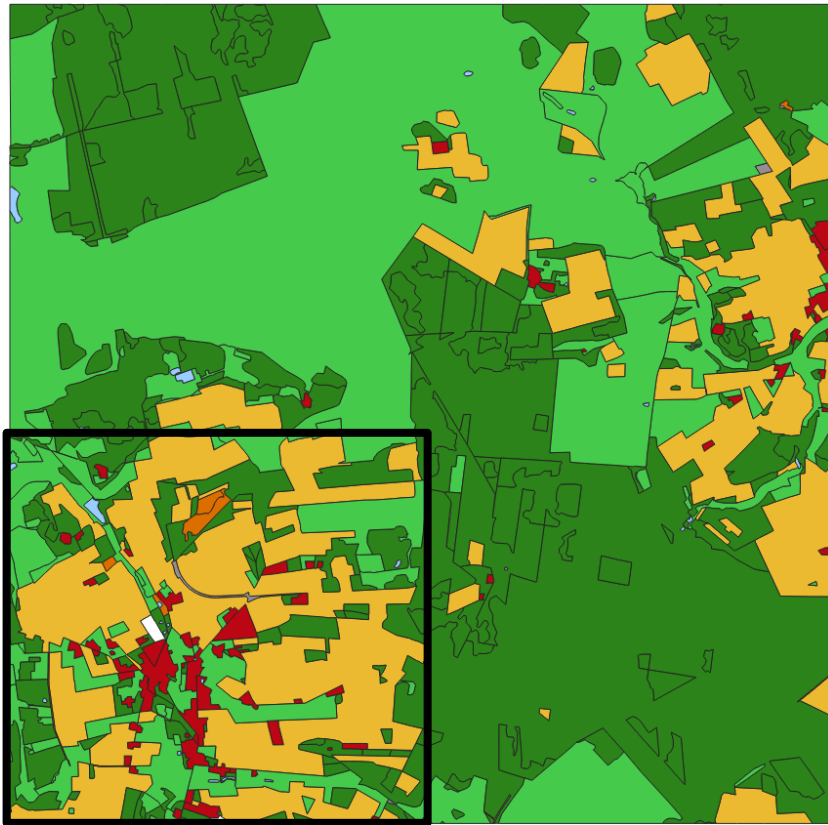
prompts
per class

semantic
segmentation as
a combination of
all class-wise
segmentations

Comparison between ATKIS and
semantic segmentation

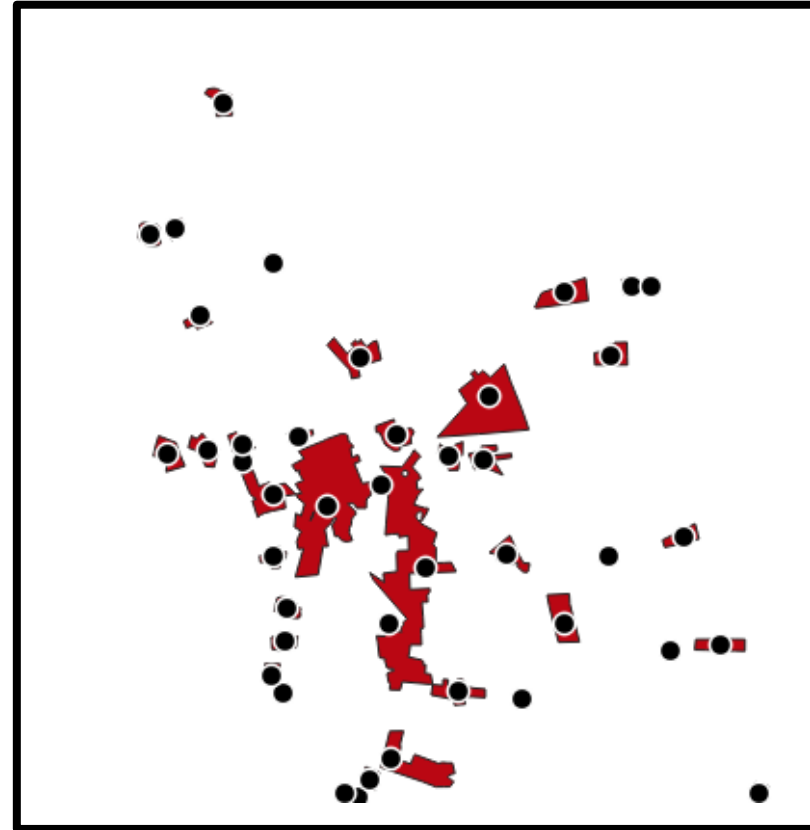
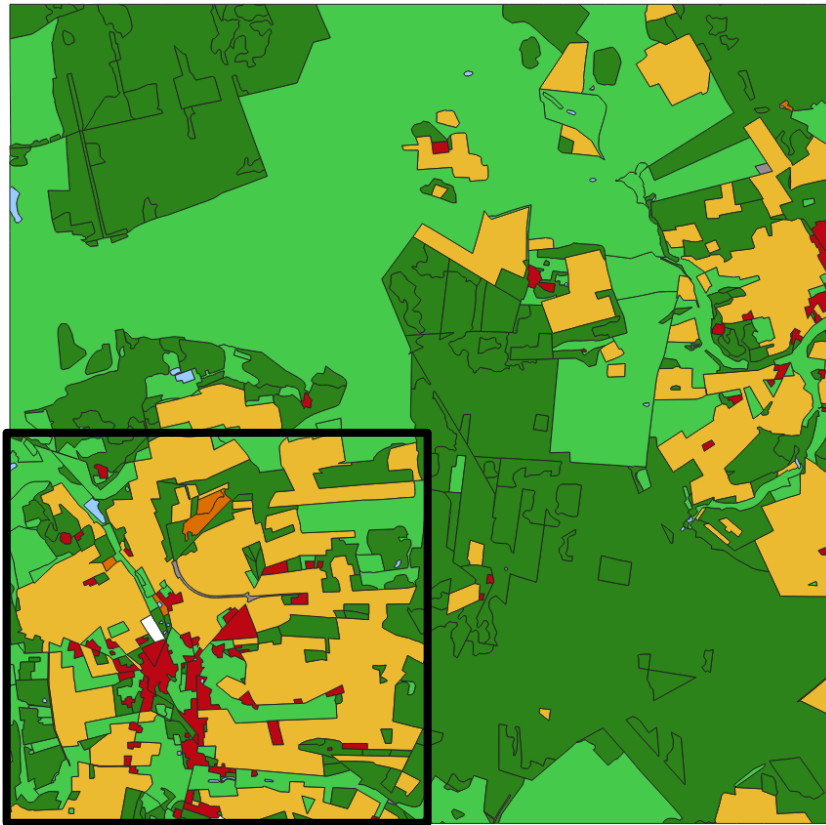
Prompt generation

- (Prior) Location information for prompting from database
- Class wise polygon selection



Prompt generation: points

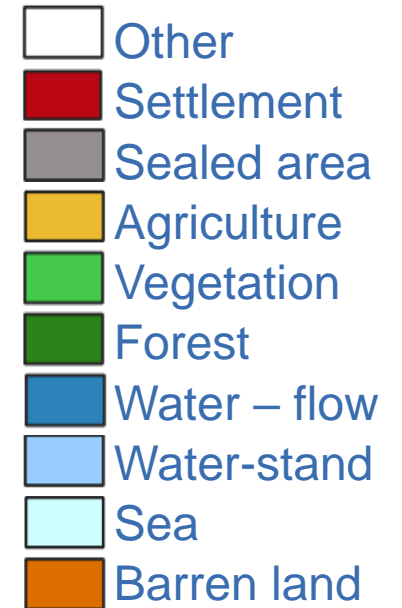
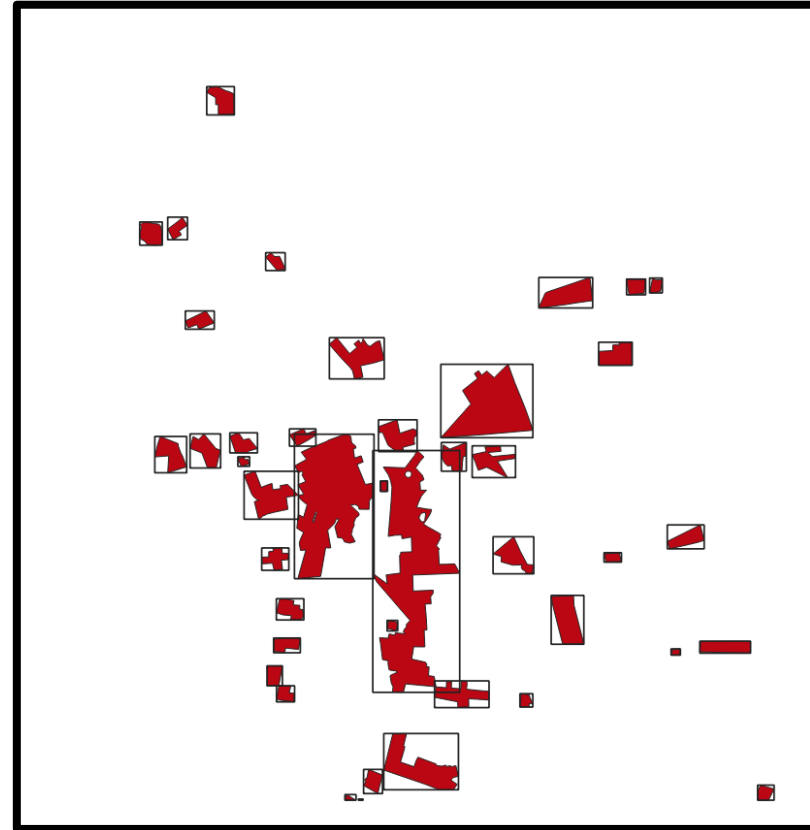
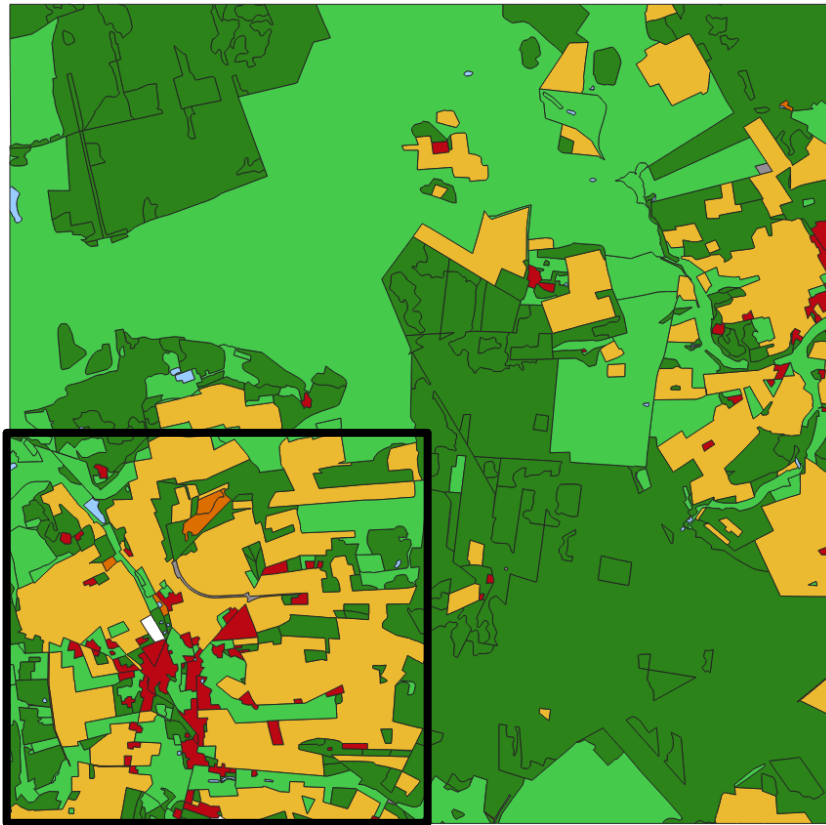
- Representative point of each polygon
 - Guaranteed to be within geometry



- Other
- Settlement
- Sealed area
- Agriculture
- Vegetation
- Forest
- Water – flow
- Water-stand
- Sea
- Barren land

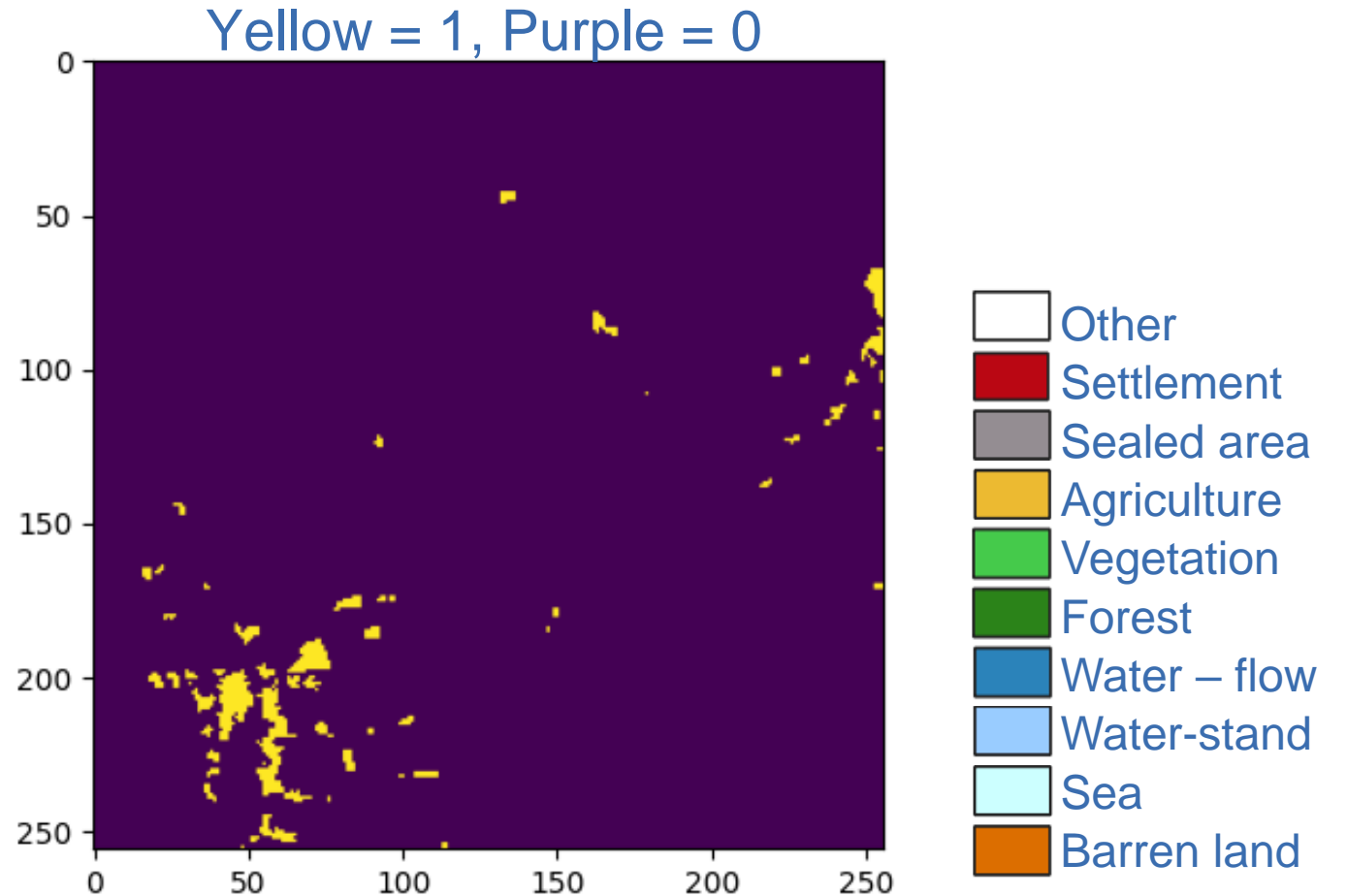
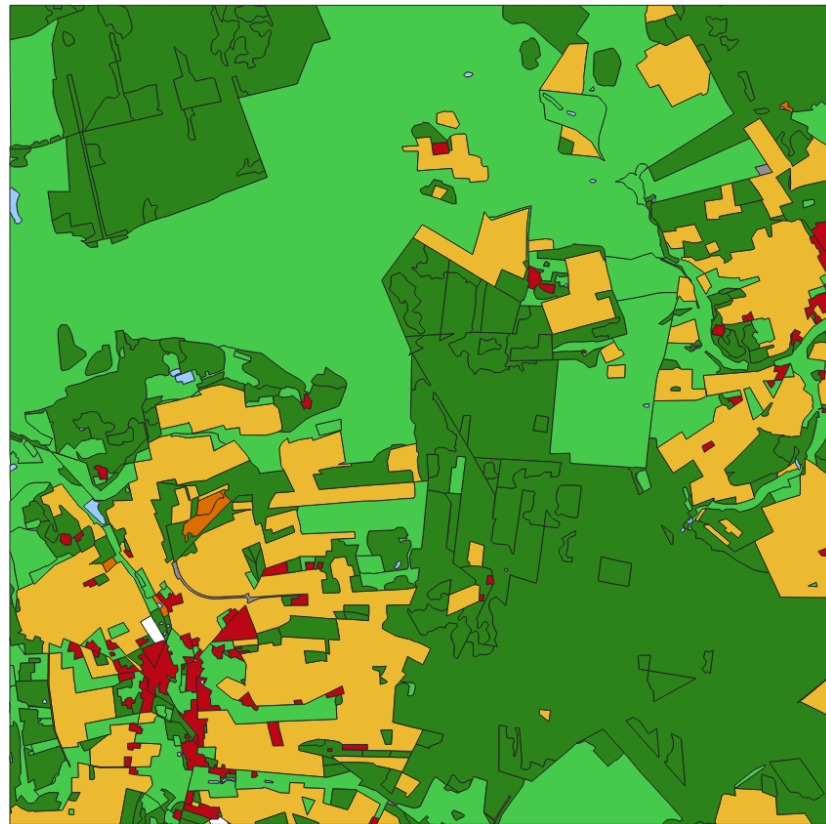
Prompt generation: boxes

- Boundaries of geometry
 - Minimum and maximum values for x and y



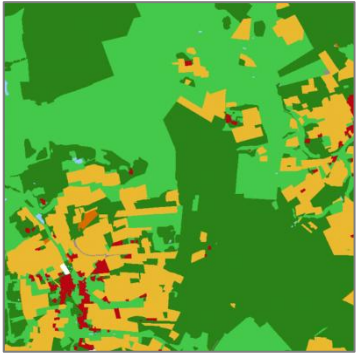
Prompt generation: mask

- Binary mask with 4 times lower resolution than input image



Example: box prompt

ATKIS objects

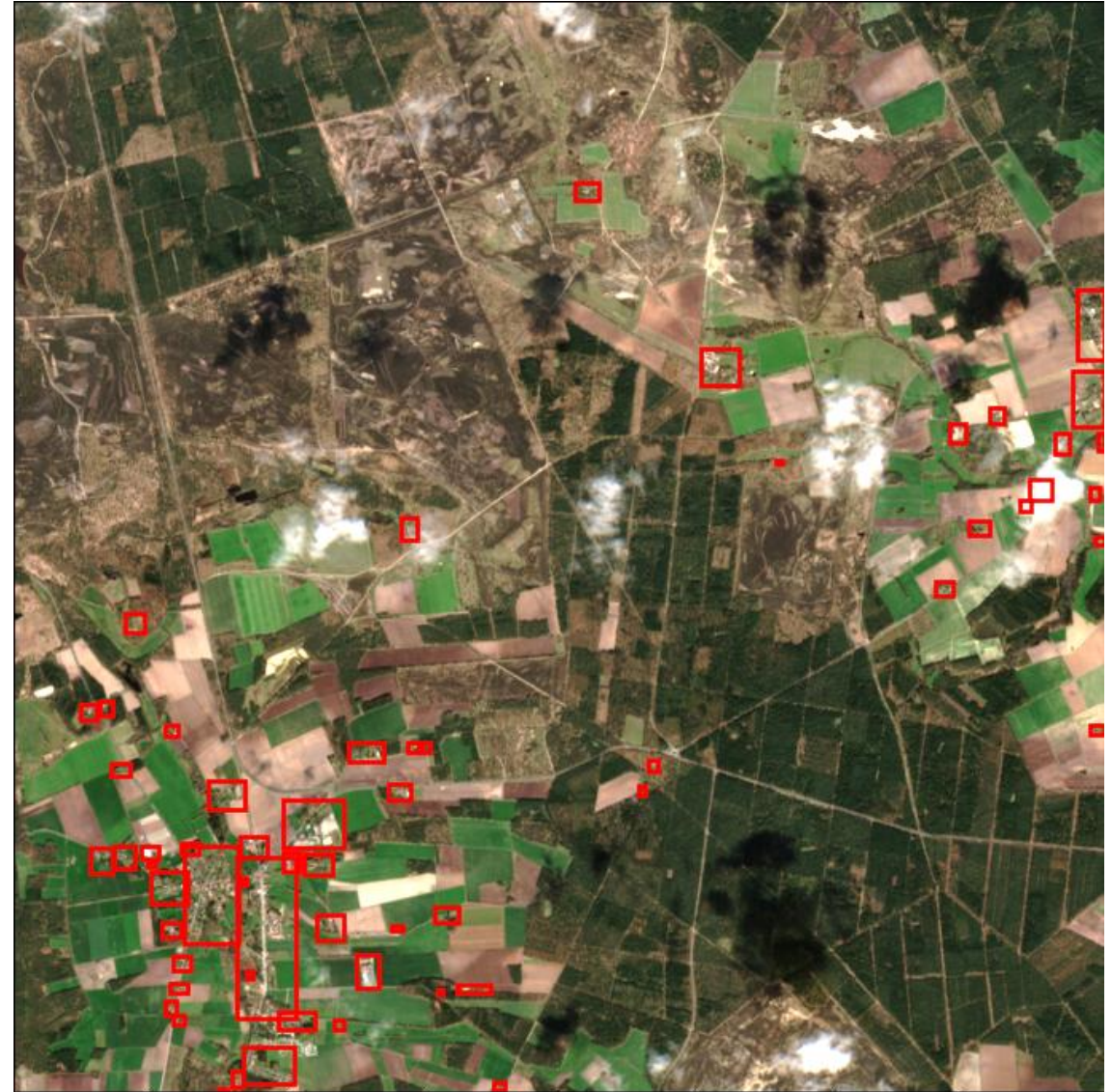


Sentinel-2 image



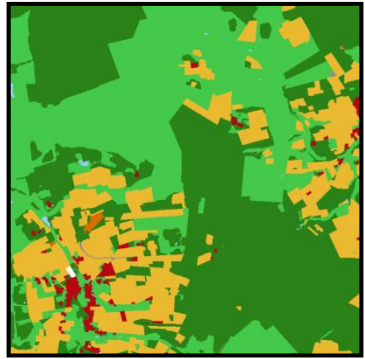
prompt
generation

box
prompt
per object
of a class

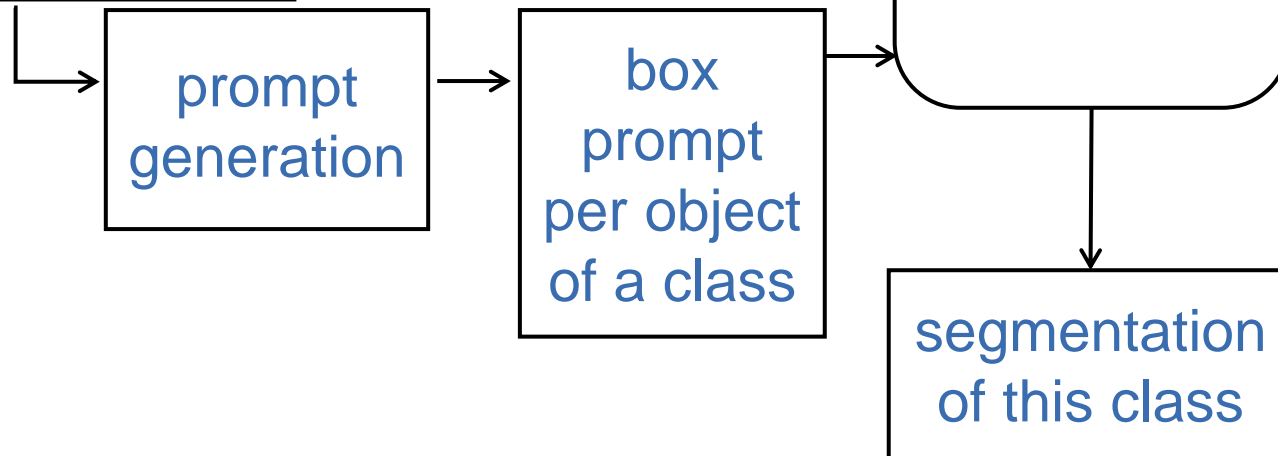


Segmentation masks for box prompt

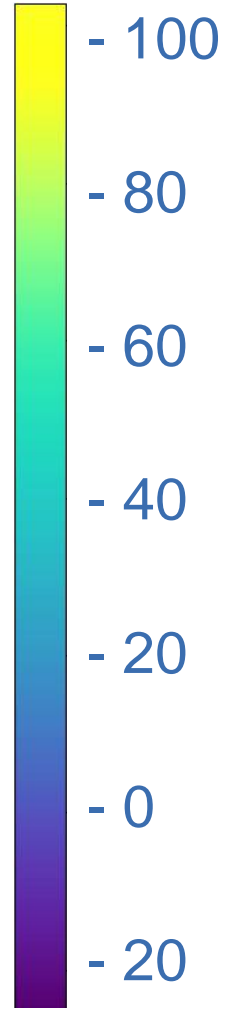
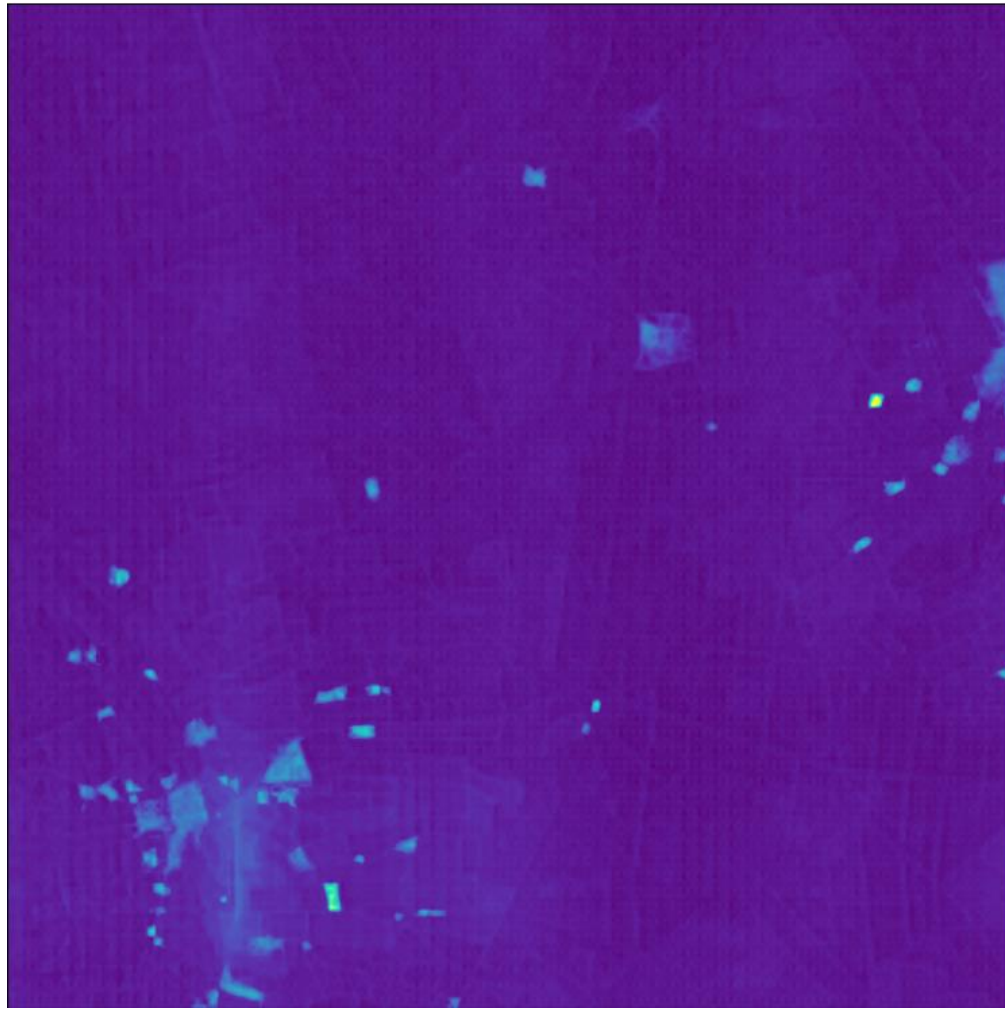
ATKIS objects



Sentinel-2 image



Logits for box prompt



Combination of logits

ATKIS objects

Sentinel-2 image

logits



SAM 2

per class
segmentation
/logits

per class



prompt
generation

prompts
per class

semantic
segmentation as
a combination of
all class-wise
segmentations

Comparison between ATKIS and
semantic segmentation



Experiments – data

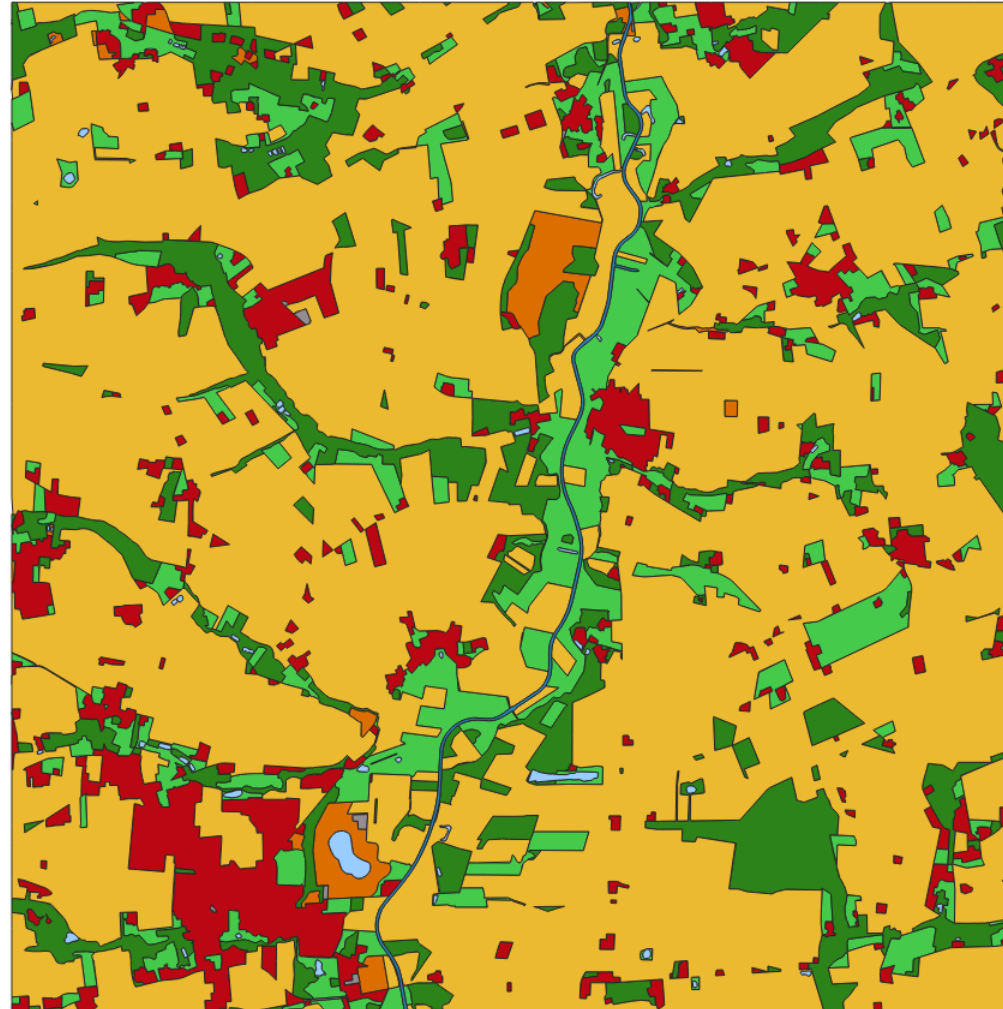


Sentinel-2 image

- True color images
- 8x8 km tiles
- Cloud free
- Images from the end of March 2019
 - Focus on monotemporal images

Experiments – data

- Corresponding polygon data from ATKIS
- 10 classes
- Data from 31st of March 2019
- Use for
 - Prompt generation
 - Reference for evaluation



ATKIS (reference data)

Experiments – setup

- Different prompt types and combinations
 - Points
 - Boxes
 - Masks
 - Points and boxes
 - Points and masks
 - Boxes and masks
 - Points, boxes and masks
- Evaluation metrics
 - F1-score and mean F1-score
 - Overall accuracy

Evaluation

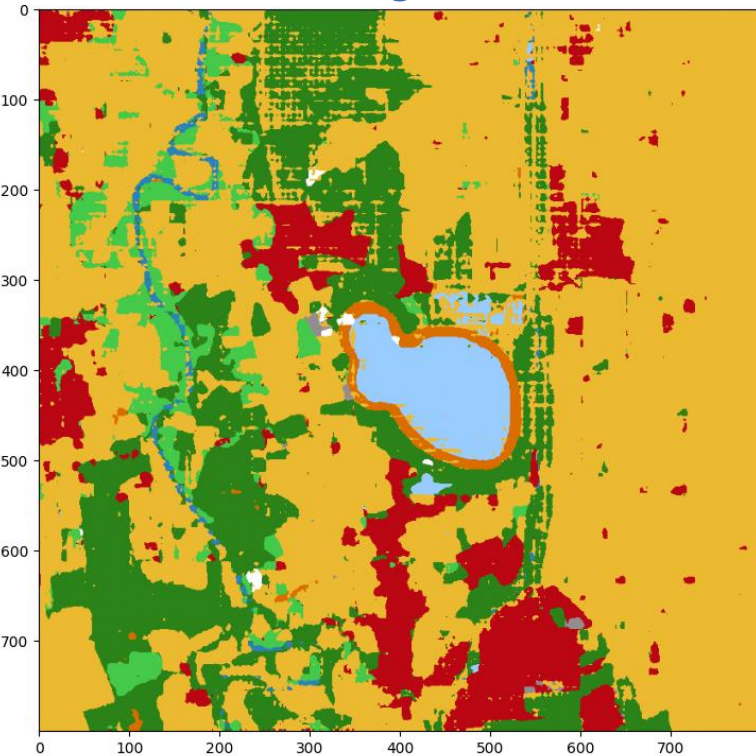
Prompt types	mF1-Score [%]	Overall accuracy [%]
Points	26,4	24,3
Boxes	59,1	70,6
Masks	59,9	75,5
Points and boxes	60,1	71,7
Points and masks	29,3	28,8
Boxes and masks	60,1	72,2
Points, boxes and masks	60,9	73,2

Evaluation: Class specific

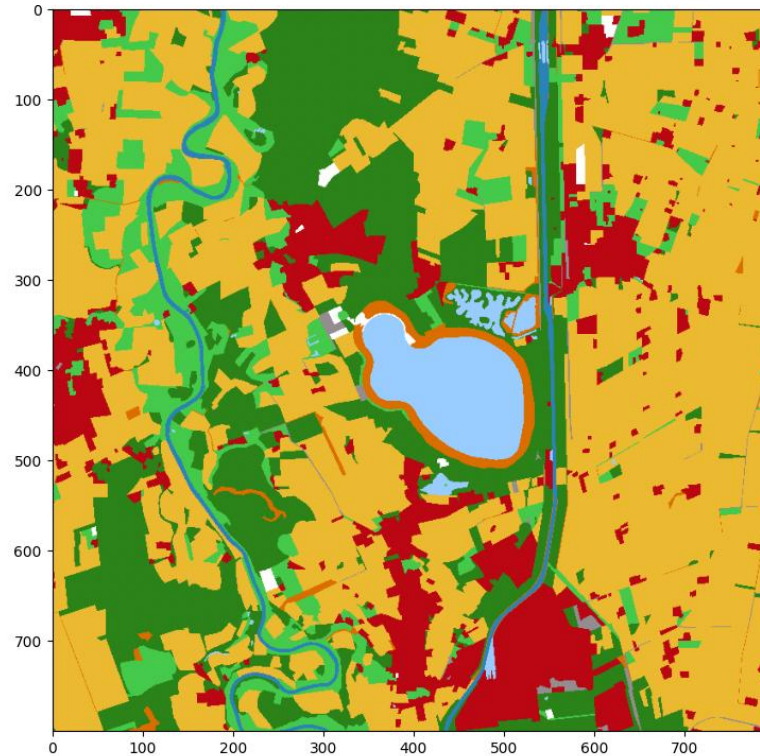
Prompt types	Settlement F1-Score [%]	Forest F1-Score [%]	Water- flow F1-Score [%]
Points	22,5	35,4	40,1
Boxes	78,8	83,5	36,9
Masks	62,8	79,2	50,8
Points and boxes	79,3	84,8	38,5
Points and masks	26,6	38,6	42,1
Boxes and masks	78,6	85,3	40,9
Points, boxes and masks	79,6	85,8	44,8

Qualitative results – mask prompt

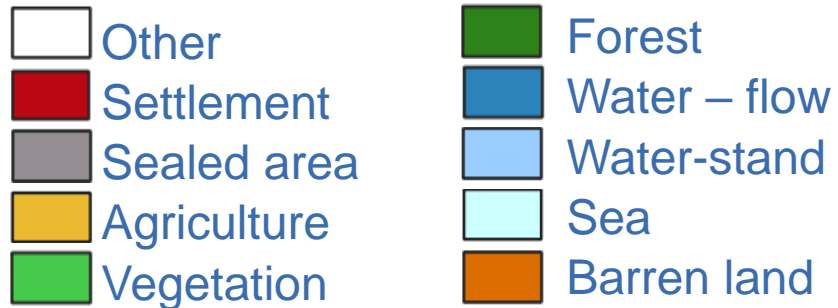
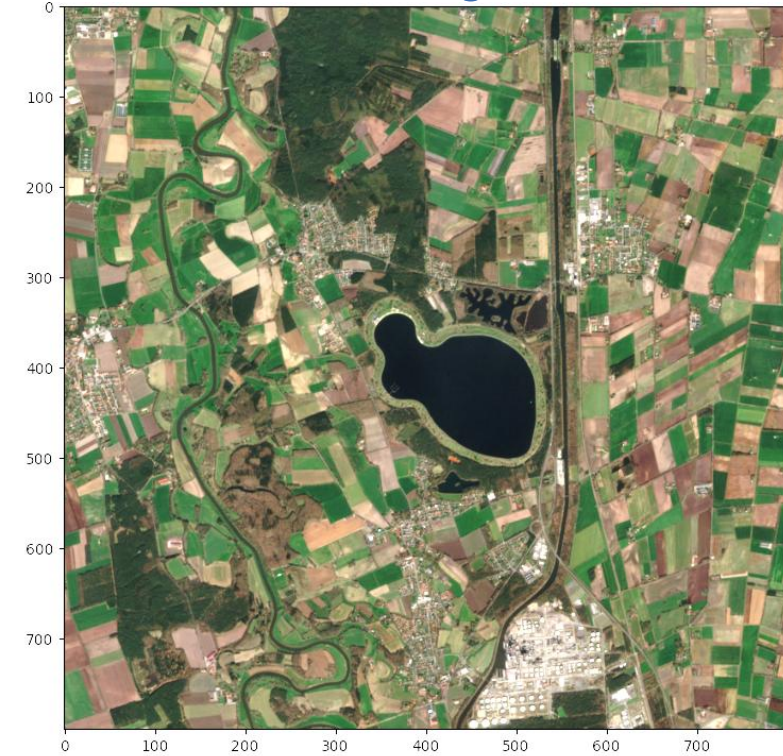
semantic segmentation



ATKIS reference



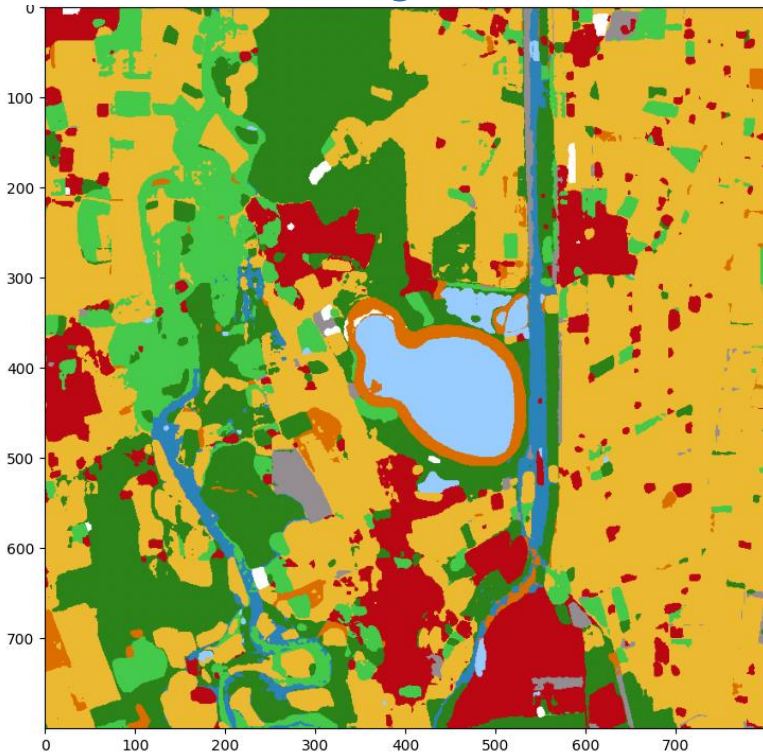
Sentinel-2 image



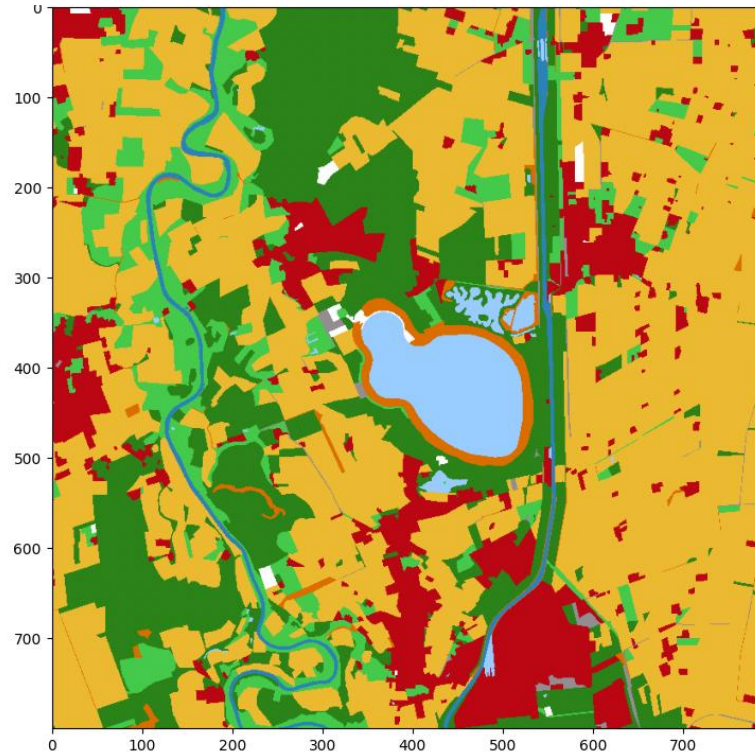
8 km

Qualitative results – box prompt

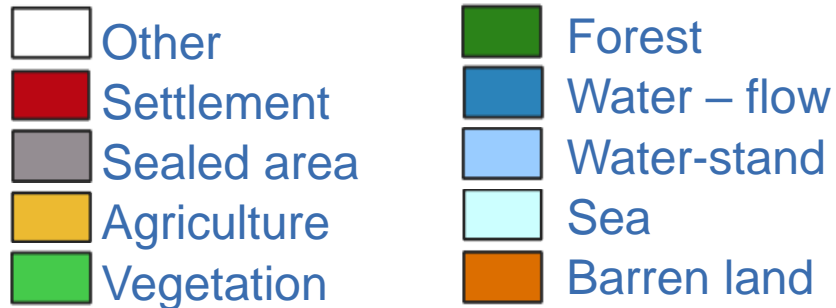
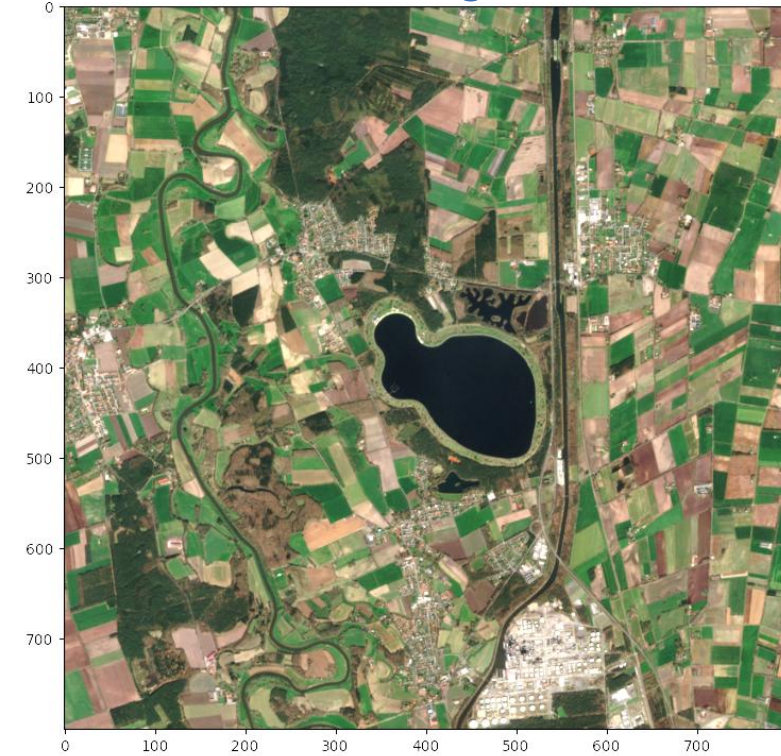
semantic segmentation



ATKIS reference



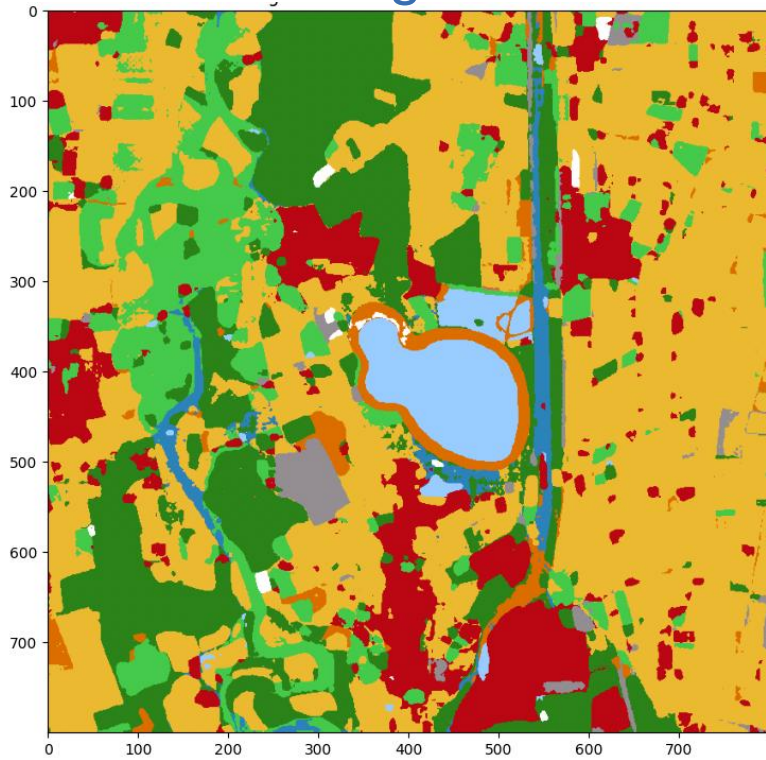
Sentinel-2 image



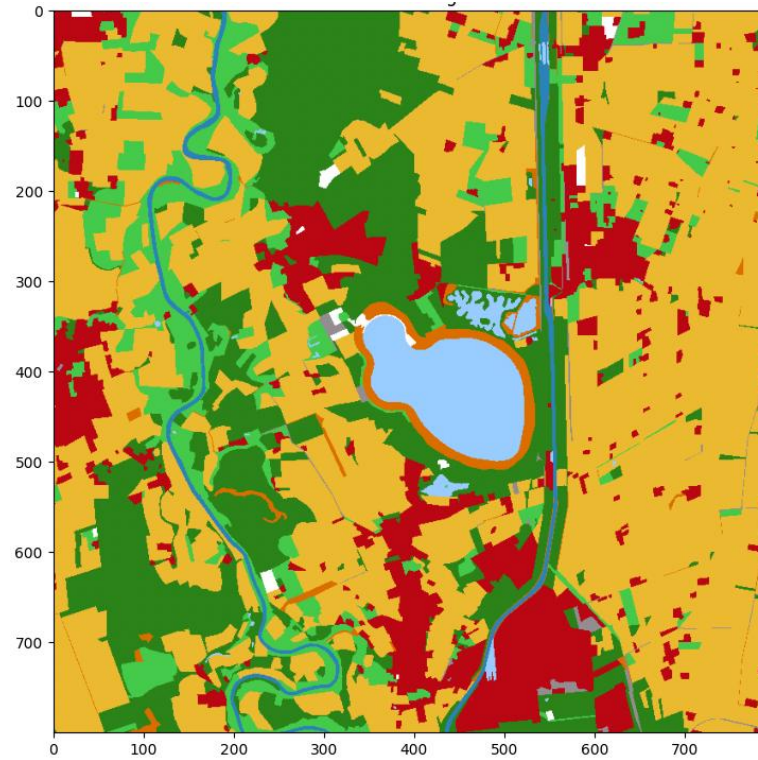
8 km

Qualitative results – points, boxes and masks prompts

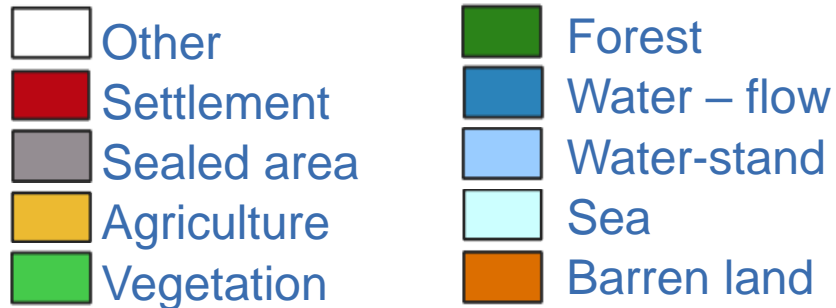
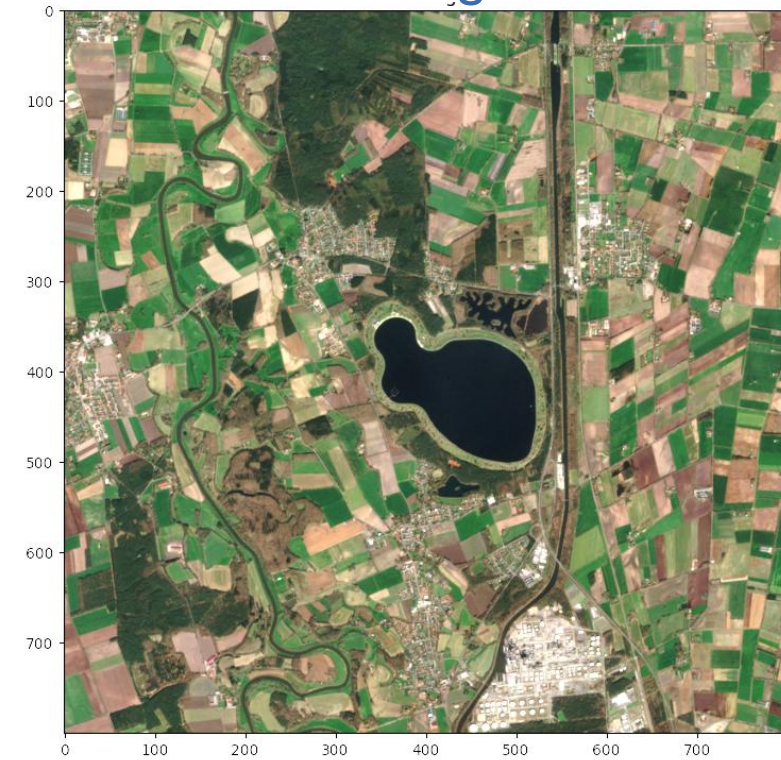
semantic segmentation



ATKIS reference



Sentinel-2 image



8 km

Conclusion and further steps with SAM 2

- Conclusion:
 - Zero-shot segmentation with SAM 2 can reach around 60 % mean F1-score
 - Point prompts perform worst
 - Bounding boxes enlarge “search” area
- Further steps with SAM 2:
 - Extend the current method to “video” segmentation – satellite image time series
 - Optimization of prompts depending on class

Other potential directions of future research

- Change focus from semantic segmentation to change detection
 - Comparison of feature vectors (of objects?)
 - From zero- to few-shot learning?
- Which other Vision Foundation models or Foundation models for remote sensing might be interesting?
 - Use the potential of more channels of remote sensing images
- How can I handle incorrect ATKIS data when used as prior knowledge or training data?
How does this affect the segmentation result?
- How do I work with few class changes in time series data?

Literature

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